EAST Search History

EAST Search History (Prior Art)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	2	("4546293").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 09:41
L2	2	("4707650").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 09:44
L7	43	"736962"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:47
L8	2	("5789893").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 09:49
L9	4132	advance adj angle$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:50
L10	10772740	control$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:50
L11	2520889	correct$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:50
L12	3807375	motor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:51
L13	8524942	position	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:51

L14	698	l9 and l10 and l11 and l12 and l13	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:51
L16	116	l14 and predetermin $3 and rotor and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 09:53
L22	1	speed$1 and control $3 and memory and rotor and motor and map and advance adj angle and correct$3 adj factor and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 10:50
L24	3	speed$1 and control $3 and memory and rotor and motor and map and advance adj angle and angle near correct$3 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 10:51
L25	4	("7007762").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 10:53
L26	25	("3908130" | "4072888" | "4316512" | "4455514" | "4546293" | "4633158" | "4641066" | "4922169" | "5115174" | "5287044" | "5298839" | "5360073" | "5589746" | "5637968" | "5701065" | "5982133" | "6134973" | "6239567" | "6424798" | "6536536" | "6538403").PN. OR ("7007762").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2010/04/19 10:53

L27	447737	conrtol adj map$4 or law	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:06
L28	1	l27 and speed$1 and control$3 and memory and rotor and motor and advance adj angle and angle near correct$3 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:06
L30	3	map$4 and speed$1 and control$3 and memory and rotor and motor and advance adj angle and angle near correct$3 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:17
L31	7	advance adj angle and correct$3 adj factor and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:19
L38	0	control adj map and advance adj angle and angle adj correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:27
L44	963	(318/799).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:33
L45	0	l44 and advance adj angle and correct$3 adj factor and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:33
L46	0	l44 and advance adj angle and angle near correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:33

L47	0	l44 and advance adj angle and angle adj correct$3 and speed $1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:34
L48	0	l44 and advance adj angle and map$4 and correct$3 and speed $1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:34
L50	221	(318/437).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:43
L51	0	l50 and advance adj angle and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:44
L53	0	advance adj angle near memory and correct$3 and speed $1 and control$3 and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:44
L54	8	advance adj angle near control$3 and correct$3 and speed $1 and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:45
L55	2	advance adj angle and lead and lag near angle and speed$1 and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:49
L56	14	advance adj angle and phase adj advance and correct$3 and speed$1 and rotor and motor and wind $4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:51

L57	144	(318/400.12).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:56
L58	0	l57 and advance adj angle and phase adj advance and correct $3 and speed$1 and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:56
L59	0	l57 and advance adj angle and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:57
L60	0	l57 and advance adj angle and map$4 and correct$3 and speed $1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:57
L61	0	l57 and advance adj angle and angle adj correct$3 and speed $1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:57
L62	749	(318/700).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 11:58
L63	0	l62 and advance adj angle and angle adj correct$3 and speed $1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:58
L64	0	l62 and advance adj angle and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 11:58

L73	2	("7443125").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:44
L74	3	("4168455").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:45
L75	2	("4611157").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:45
L76	2	("5012172").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:46
L77	2	("5206575").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:47
L78	2	("5450306").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:49
L79	2	("5640073").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:51
L80	2	("5903128").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:52
L81	2	("6072302").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 13:53

L82	61	" | ""6084786"" | ""6128204"" | ""6153956"" | ""6166511"" | ""6201368"" | ""6222335"" | ""6288514"" | ""6313597"" | ""6316918"" | ""6380719"" | ""6486644"" | ""6490752"" | ""65"("45443" | "6586904" | "6593720" | "6603672" | "6642681" | "6707265" | "6759826" | "6801441" | "6803739" | "6819008" | "6864658" | "6879062" | "6958589" | "7005828" | "7007762" | "7035123" | "7076830" | "7102903" | "7109605" | "7233873" | "7250734" | "7305569" | "7443125" | "RE40250").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:57
L83	0	l82 and advance adj angle$1 and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:57
L84	0	l82 and advance adj angle$1 and control$3 and memory and rotor and motor and wind$4 and speed$1 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:58
L85	0	l82 and advance adj angle$1 and control$3 and memory and $1otor and wind$4 and speed$1 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 13:58

L91	2	EP adj "129007"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:14
L92	0	EP adj "0505159"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:14
L93	2	EP adj "505159"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:15
L94	2	EP adj "748038"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 14:20
L105	276	(318/779).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 15:25
L106	0	l05 and advance adj angle$1 and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:25
L107	0	l105 and advance adj angle$1 and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:26
L108	144	(318/400.12).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 15:26
L109	0	l108 and advance adj angle$1 and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:26

L110	749	(318/700).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2010/04/19 15:26
L111	0	l110 and advance adj angle$1 and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2010/04/19 15:27
S1	2	("4494055").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:35
S2	4	("4223258").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:36
S3	3	("4236102").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:37
S4	2	("4168455").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:37
S5	2	("4611157").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:38
S6	2	("4772839").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:39
S7	2	("5724477").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:39
S8	2	("6222335").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:47

S9	2	("5298839").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 09:48
S10	2	("5796226").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 11:39
S11	827	(318/701).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2008/01/03 11:39
S12	1352368	motor.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:39
S13	5036	SRM or switch$2 adj reluctance.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:40
S14	9187760	control$3 or ECU.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:40
S15	313182	rotor.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:40
S16	3892636	coil or phase or winding.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:41
S17	4197364	position$3.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:41
S18	863815	map or table.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:41

S19	3563744	speed or torque.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:42
S20	1127926	angle.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:42
S21	10	S12 and S13 and S14 and S15 and S16 and S17 and S18 and S19 and S20	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/03 11:44
S22	3	vaccum adj motor.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:37
S23	26962	cleaning adj device. ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:36
S24	5036	SRM or switch$2 adj reluctance.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:36
S25	1	S23 and S24	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:36
S26	437778	vacuum.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:38
S27	637565	clean$3.ab.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:38
S28	16	S24 and S26 and S27	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/01/04 10:38

S29	1	"10588289"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 14:21
S30	12	("4987546" | "5023527" | "5023528" | "5113125" | "5124625").PN. OR ("5796226").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2008/09/25 15:33
S31	445597	map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:56
S32	6269524	machine or motor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:57
S33	11237	(on or off) near angle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:57
S34	17321	angle near correct$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:57
S35	451	desir$2 near power	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:58
S36	8644	(desir$2 or actual) near power	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:58
S37	0	S31 and S32 and S33 and S34 and S36	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:59
S38	0	S31 and S32 and S33 and S34 and S35	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:59

S39	39	S31 and S32 and S33 and S34	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 15:59
S40	13	S39 and power and desir$2	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/25 16:00
S41	6	"6819008"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/09/26 11:12
S42	5	predetermin$3 and angle near correct$3 and advanc$2 near angle and rotor and stator and control$3 and map$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 07:41
S43	12	("4987546" | "5023527" | "5023528" | "5113125" | "5124625").PN. OR ("5796226").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 08:00
S44	3	map$4 and advance near angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 08:16
S45	5	map$4 and advance near angle and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 08:16
S46	42	map$4 and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 08:17
S47	13	("4942345" | "5446359" | "5461295" | "5532567" | "5589752" | "5652493" | "5767638" | "5796226" | "5814965" | "5864218").PN. OR ("6040678").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 09:04

S48	51	("3967173" | "4739240" | "4743815" | "5140243" | "5291115" | "5448149" | "5469039" | "5475289" | "5545964" | "5563488" | "5638265" | "5677607" | "5694010" | "5705918" | "5796226" | "5841262" | "5936386" | "5969962" | "6008601" | "6011377" | "6051942" | "6150778" | "6153993" | "6157160" | "6191676" | "6285148" | "6288514" | "6472842" | "6509710" | "6593720" | "6650082" | "6683427" | "6683428" | "6707265" | "6707266" | "6710559" | "6710564" | "6724162" | "6724168" | "6734646" | "6737820" | "6747426" | "6753663" | "6756749" | "6756757" | "6762574" | "6771035").PN. OR ("6819008").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 09:55
S49	10	("1292007").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 10:15

S50	844	(318/701).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 10:54
S51	1	S50 and map$4 and advance near angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 10:54
S52	3	S50 and map$4 and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 10:55
S53	165	(318/712).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:12
S54	0	S53 and map$4 and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:12
S55	932	(318/799).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:12
S56	1	S55 and map$4 and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:13
S57	162	(318/715).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:22
S58	1	S57 and map$4 and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:22
S59	511	(318/721).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:24

S60	2	S59 and map$4 and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:24
S61	1	S59 and map$4 and advance near angle and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:32
S62	1602	(318/432).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:34
S63	1	S62 and map$4 and angle near correct$3 and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:34
S64	1	S62 and map$4 and advance near angle and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:34
S65	352	(318/433).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:37
S66	1	S65 and map$4 and advance near angle and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:37
S67	711	(318/700).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/03/03 11:39
S68	2	S67 and map$4 and advance near angle and rotor and stator and pole$1	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/03 11:39
S69	7	("4734633" | "5057759" | "5777447" | "6462492" | "6555988" | "6674261").PN. OR ("6803739").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/03/03 11:40

S70	14362926	one or single near angle near (correct$3 or adjust$4) same factor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 14:50
S71	1	S70 and motor and control adj map and energiz$3 and turn near angle and predetermin$3 and memory	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 14:52
S72	0	angle near factor and conduct$3 near angle and turn near on	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:03
S73	0	correct$3 near factor and conduct$3 near angle and turn near on	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:03
S74	0	adjust$4 near factor and conduct$3 near angle$1 and control near map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:04
S75	1	adjust$4 near angle$1 and factor and conduct $3 near angle$1 and control near map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:05
S76	0	correct$3 near factor and conduct$3 near angle$1 and control near map and speed $1 and rotor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:06
S77	0	adjust$4 near factor and conduct$3 near angle$1 and control near map and speed $1 and rotor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:06
S78	27	angle same factor and control near map and speed$1 and rotor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 15:08
S79	2	("7443125").PN.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:05

S80	2	switch$2 near machine and angle near compensat$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:09
S81	9	("5724477" | "6291949" | "6396237" | "6495985").PN. OR ("6586904").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/10/22 16:10
S82	3	switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:13
S83	856	(318/701).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:13
S84	1	S83 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:14
S85	3568	(318/696).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:14
S86	0	S85 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:14
S87	483	(318/400.01).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:14
S88	0	S87 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:15
S89	202	(318/438).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:15

S90	0	S89 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:15
S91	1053	318/799	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:16
S92	0	S91 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:16
S93	115	(318/290).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:16
S94	0	S93 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:17
S95	1663	(318/432).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:18
S96	0	S95 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:18
S97	524	(318/430).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:18
S98	0	S97 and switch$2 near machine and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:18
S99	2	S91 and angle near correct$3 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:19

S100	0	S91 and angle near adjust$4 and rotor and speed and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:26
S101	0	S95 and angle near correct$3 and rotor and speed and map and turn near on	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:27
S102	2	S95 and angle near correct$3 and rotor and speed and map and control$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:27
S103	219	(318/437).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 16:27
S104	0	S103 and angle near correct$3 and rotor and speed and map and control$3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:27
S105	136	angle near correct$3 and rotor and speed and map and control $3	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:28
S106	30	S105 and speed$1 and rotor and predetermin$3 near angle	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:29
S107	16	S106 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:29
S108	37	angle near correct$3 and rotor and speed and map and control $3 and motor with wind$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:33
S109	23	S108 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 16:33

S110	693	(173/217).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/10/22 17:26
S111	3	S110 and angle near correct$3 and rotor and speed$1 and map and control$3 and motor with wind$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:26
S112	1	angle near correct$3 and rotor and range near speed$1 and map and control$3 and motor with wind$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:48
S113	1	angle near correct$3 and rotor same range near speed$1 and map and control$3 and motor with wind$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:49
S114	24	angle near correct$3 and rotor same speeds and map and control$3 and motor with wind$4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:50
S115	15	S114 and @py<="2004"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/10/22 17:50
S120	24	("3908130" | "4072888" | "4316512" | "4455514" | "4546293" | "4633158" | "4641066" | "4922169" | "5115174" | "5287044" | "5298839" | "5360073" | "5589746" | "5637968" | "5701065" | "5982133" | "6134973" | "6239567" | "6424798" | "6536536" | "6538403").PN. OR ("7007762").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2009/12/03 12:04

S121	2	advance near angle and angle near correct $3 and range near speed$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/03 12:16
S122	20	advance near angle and angle near correct $3 and speed$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/03 12:16
S124	233	(318/400.23).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:12
S125	144	(318/400.12).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:13
S126	1	S124 and advance near angle and angle near correct$3 and speed$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:13
S127	0	S125 and advance near angle and angle near correct$3 and speed$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:13
S128	104	(318/400.32).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:14
S129	0	S128 and advance near angle and angle near correct$3 and speed$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:14
S130	858	(318/701).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2009/12/04 12:14
S131	1	S130 and advance near angle and angle near correct$3 and speed$1 and rotor and motor and map	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/12/04 12:14

EAST Search History (Interference)

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L18	63	speed$1 and control$3 and memory and advance adj angle near correct$3 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:26
L19	2	speed$1 and control$3 and memory and rotor and motor and map and advance adj angle and angle adj correct$3 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:48
L20	0	speed$1 and control$3 and memory and rotor and motor and map and advance adj angle and angle near correct$3 adj factor and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:49
L21	1	speed$1 and control$3 and memory and rotor and motor and map and advance adj angle and correct$3 adj factor and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 10:49
L32	6	advance adj angle and correct$3 adj factor and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:19
L34	1	angle near map$4 and correct$3 adj factor and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:26
L35	0	on near advance adj angle and map$4 and correct$3 adj factor and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:26
L39	0	control adj map and advance adj angle and angle adj correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:28

L41	0	control adj table$1 and advance adj angle and angle adj correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:29
L42	0	control adj table$1 and advance adj angle and angle near correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:29
L43	1	table$1 and advance adj angle and angle near correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:29
L49	45	("4223261" | "4429262" | "4447771" | "4490661" | "4498037").PN. OR ("4651068").URPN.	US-PGPUB; USPAT	OR	ON	2010/04/19 11:35
L52	0	advance adj angle near memory and correct$3 and speed$1 and control $3 and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:44
L65	0	advance adj angle adj profile and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:58
L66	0	advance adj angle adj profile and correct$3 adj factor and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:58
L67	2	advance adj angle and profile and correct$3 adj factor and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py<="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 11:59

L68	0	advance adj angle and profile and conduct$3 adj angle$1 and correct$3 and speed$1 and control$3 and memory and rotor and motor and wind$4 and @py< ="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 12:00
L69	3	advance adj angle and conduct$3 adj angle$1 and correct$3 and speed $1 and control$3 and memory and rotor and motor and wind$4 and @py< ="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 12:00
L70	19	advance adj angle and range near speed$1 and control$3 and memory and rotor and motor and wind$4 and @py< ="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 12:10
L71	63	("4270074" | "4368411" | "4489267" | "4602882"). PN. OR ("4739240"). URPN.	US-PGPUB; USPAT	OR	ON	2010/04/19 12:31
L72	2	correct$3 adj factor near advance adj angle$1 and motor	US-PGPUB; USPAT	OR	ON	2010/04/19 13:07
L86	1	correct$3 near advance adj angle$1 and control$3 and memory and $1otor and wind$4 and speed$1 and @py< ="2004"	US-PGPUB; USPAT; UPAD	OR	ON	2010/04/19 13:59
S116	0	correct$3 near factor and conduct$3 near angle and turn near on	USPAT; UPAD	OR	ON	2009/10/22 15:04
S117	0	correct$3 near angle$1 and control near map and speed$1 and rotor and conduct$3	USPAT; UPAD	OR	ON	2009/10/22 16:08
S118	0	adjust$3 near angle$1 and control near map and speed$1 and rotor and conduct$3	USPAT; UPAD	OR	ON	2009/10/22 16:08
S119	0	switch$2 near machine and angle near compensat $3 and rotor and speed and map	USPAT; UPAD	OR	ON	2009/10/22 16:09
S123	1	advance near angle and angle near correct$3 and range near speed$1 and rotor and motor and map	USPAT; UPAD	OR	ON	2009/12/03 12:15

| S132 | 9 | advance near angle and angle near correct$3 and speed$1 and rotor and motor and map | USPAT; UPAD | OR | ON | 2009/12/04 12:15 |

4/19/2010 3:27:54 PM
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